NOVOHALL Rotary Sensor Touchless

# RFE-3200

Current Mobile Applications





## Special Features

- Touchless hall technology
- Electrical range up to 360°
- 2 part design, mechanically decoupled
- High protection class IP67, IP68, IP69K
- Resolution up to 12 bit
- Wear-free
- Temperature range -40 °C to +105 °C
- One and multi-channel versions
- Optimized for use in mobile applications with highest EMC requirements such as ISO pulses and high interferences to ISO 11452 and ECE-Standard
- Suitable for safety-related applications according to DIN EN ISO 13849
- Other configurations see separate data sheets

## Applications

- Mobile working machines (industrial trucks, construction machinery, agricultural and forestry machinery)
- Marine applications

The 2 part design consisting of sensor and magnetic position marker offers great flexibility when mounting. The absence of shaft and bearing makes the assembly much less sensitive to axial and radial application tolerances - separate couplings are obsolete. Measurements can be made transmissively through any non-ferromagnetic material. With its completely encapsulated electronics the sensor is perfectly suited for use in harsh environments. Single and multi-channel versions are available and suitable for use in safety-related applications.

Description	
Description Material	Housing: high grade, temperature resistant plastic PBT GF30 with stainless steel inserts
Mounting	With 2 pan head screws M4x18 (included in delivery)
Fastening torque of mounting	max. 200 Ncm
Electrical connection	6-pin MQS-connector, code A, tinned contact according to drawing AMP-114-18063-126, Index A1 (Connector: AMP P/N 1-967616-1)
Mechanical Data	
Dimensions	See dimension drawing
Mechanical travel	continuous

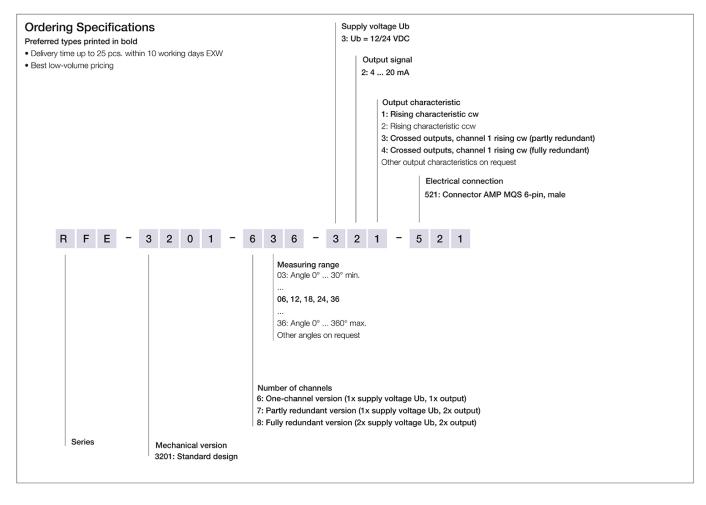


approx. 50 g

Weight



## Ordering Specifications

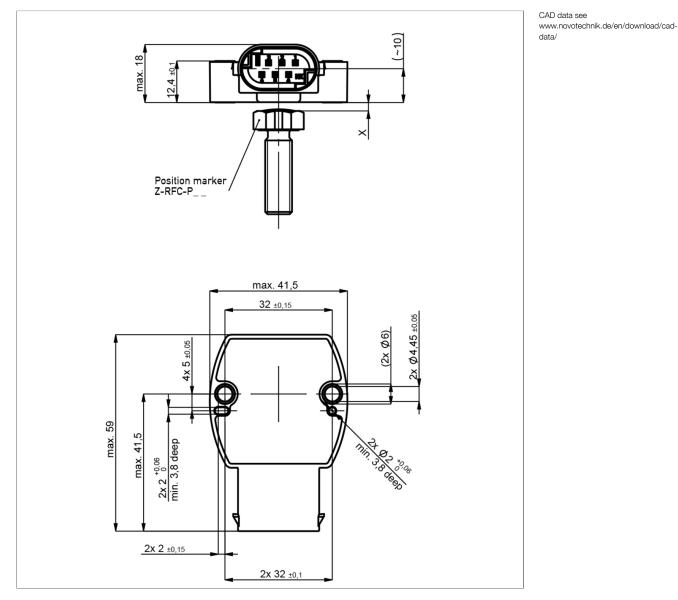


## Accessories included in delivery

• 2x Pan head screws M4x18



# Drawing





When the marking of the position marker points towards the connector, the sensor is near the electrical center position.



# **Technical Data**

Туре	RFE-3232521
	Analog current
Output signal	4 20 mA
Burden	@Ub > 13 V: ≤ 500 Ω, @Ub ≤ 13 V: ≤ 250 Ω
Number of channels	1/2
Diagnosis	activated (in case of error, output signal is outside of the plausible signal range)
Update rate	typ. 3.4 KHz
Measuring range	0 30° up to 0 360° in 10°-steps
Independent linearity	≤ ±0.5 %FS
Resolution	12 bits
Repeatability	$typ. \le \pm 0.1^{\circ}$
Hysteresis	typ. < ±0.1°
	Only measuring range 360°: typ. < 0.25° (lower hysteresis on request)
Temperature error	Measuring range 30 170°: typ. ±1.2 %FS, Measuring range ≥ 180°: typ. ±0.6 %FS
Supply voltage Ub	12/24 VDC (8 34 VDC)
Current consumption w/o load	typ. 12 mA per channel
Overvoltage protection	60 VDC (10 min.)
Polarity protection	yes (supply lines and outputs)
Short circuit protection	yes (vs. GND and supply voltage Ub)
Insulation resistance (500 VDC)	≥ 10 MΩ
Environmental Data	
Max. operational speed	Mechanically unlimited
Vibration IEC 60068-2-6	20 g, 5 2000 Hz, Amax = 0.75 mm
Shock IEC 60068-2-27	50 g, 6 ms
Protection class ISO 20653	IP67 / IP68 / IP69K
Operating temperature	-40 +105°C*
	* The max. operating temperature depends on supply voltage Ub and burden (see temp.diagram)
Life	Mechanically unlimited
Functional safety	Suitable for safety-related applications according to ISO 13849 after customer validation.
	Further safety data ( DCavg) and support for functional safety are available on request.
MTTF (IEC 60050)	726 years (one-channel), 448 years (partiy redundant, per channel) or 364 years (fully redundant, per channel)
MTTFd (EN ISO 13849-1 parts count	1453 years (one-channel), 896 years (partly redundant, per channel) or 727 years (fully redundant, per channel)
method, w/o load)	
MTTFd-certificate	https://www.novotechnik.de/en/downloads/certificates/mttfd-certificates/
Traceability	Serial number on type labeling: production batch of the sensor assembly and relevant sensor components
Conformity/Approval	CE, UKCA, E1 see https://www.novotechnik.de/en/downloads/certificates/declarations-of-conformity-eu/uk
	WEEE see https://www.novotechnik.de/en/downloads/certificates/eu-directive-weee/
EMC Compatibility	
ISO 10605 ESD (Handling/Component)	8 kV / 15 kV
ISO 11452-2 Radiated HF-fields	100 V/m
ISO 11452-5 Radiated HF-Fields, stripline	200 V/m
CISPR 25 Radiated emission	Level 5
ISO 7637-2 Transient Emissions	Level 3
ISO 7637-2 Pulses on supply lines	(1, 2a, 2b, 3a, 3b, 4, 5) Level 4
ISO 7637-3 Pulses on output lines	Level 4
EN 13309 Construction machinery	
Emission/Immunity E1	acc. to ECE-R10
ISO 13766-1/-2 Construction machinery	Any multi-channel version

 $\mathsf{FS}=\mathsf{Full}$  scale: Signal span according to electrical measuring range



## Connection Assignment

Signal	Connector	Connector	Connector
	code 5	code 5	code 5
	One-channel	Partly redundant	Fully redundant
Supply voltage Ub 1	Pin 1	Pin 1	Pin 1
GND 1	Pin 2	Pin 2	Pin 2
Signal output 1	Pin 4	Pin 4	Pin 4
Signal output 2	-	Pin 3	Pin 3
Supply voltage Ub 2	-	-	Pin 6
GND 2	-	-	Pin 5
Not assigned	Pin 3, Pin 5, Pin 6	Pin 5, Pin 6	-

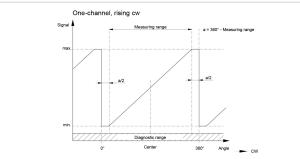




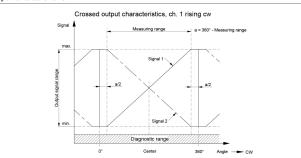
Technical Data Output Characteristics

#### Temperature Diagram Current output: max. operating temperature as a function of the supply voltage 130 125 120 115 100 90 90 85 80 75 70 65 ······ Burden 250 Ω • • • Burden 500 Ω 119°C @ 12 V / 250 Ω 105°C @ 24 V / 500 Ω 95°C @ 24 V / 250 Ω + 18 20 22 Supply voltage [V] 10 12 14 16 24 26 28 30 32 34 8

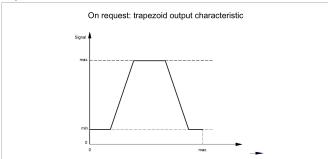
## Output characteristic



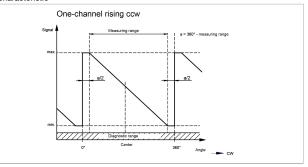
#### Output characteristic



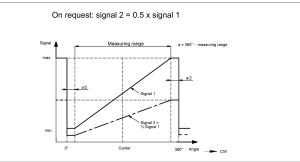
#### Output characteristic



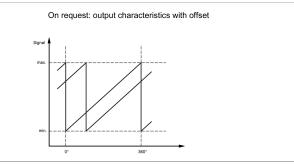
## Output characteristic



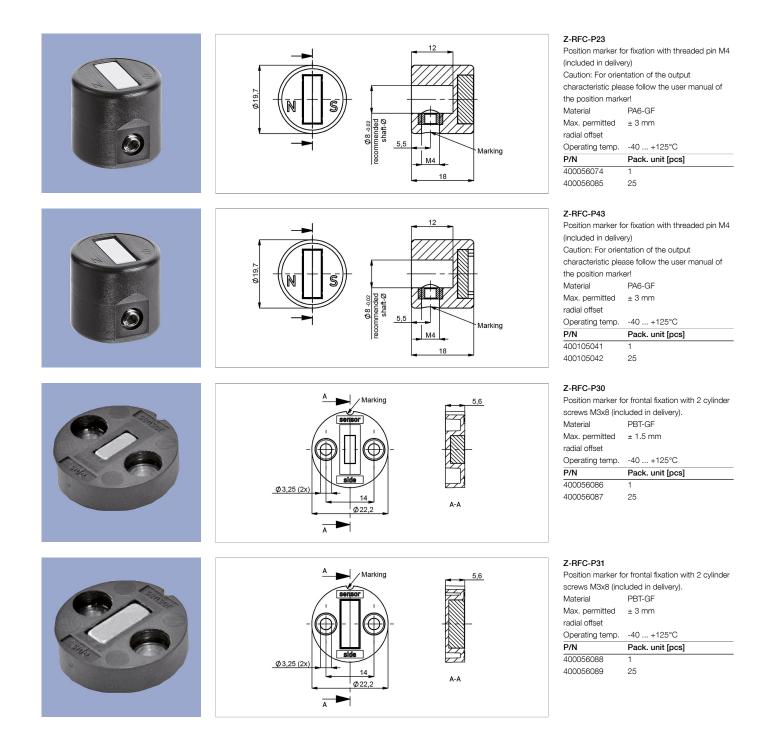
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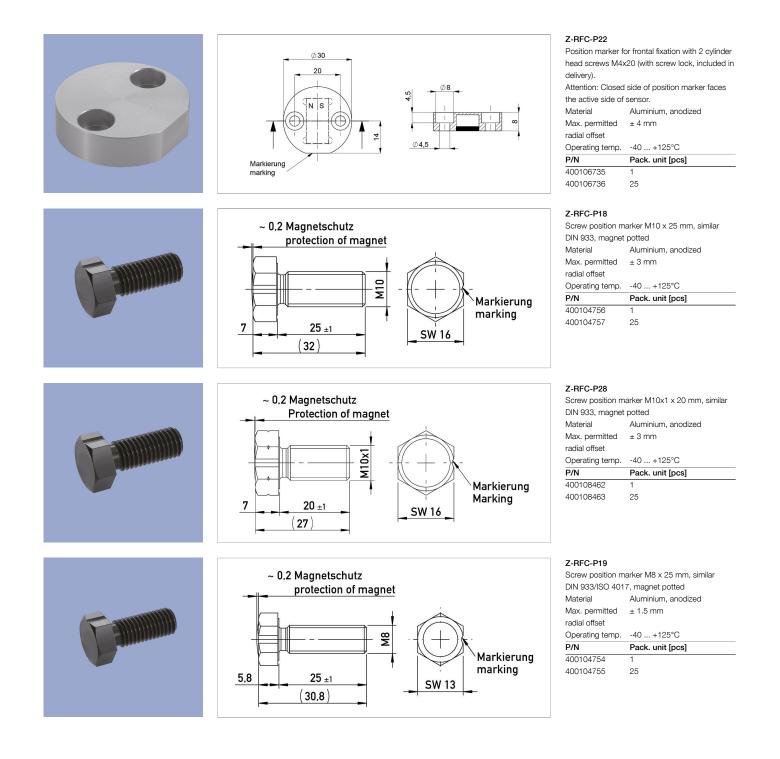
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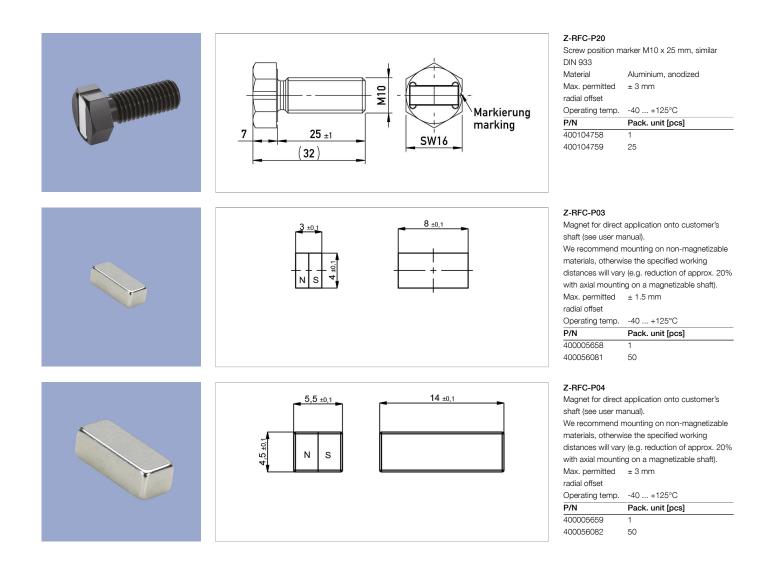










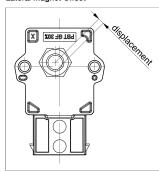




Working Distances Position Markers [mm] - One-channel Versions

Z-RFC-P03	Z-RFC-P04	Z-RFC-P18 / P28	Z-RFC-P19	Z-RFC-P20	Z-RFC-P22	Z-RFC-P23	Z-RFC-P30	Z-RFC-P31	Z-RFC-P43
0.4 1.9	2 4.7	0 4	0 1.8	2 4.7	4.1 8.9	2 4.7	0.4 1.9	2 4.7	0 2.4
Maulina Distan									
working Distar	ices Position Mark	ers [mm] - Redundar	it Versions						
Z-RFC-P03	Z-RFC-P04	Z-RFC-P18 / P28		Z-RFC-P20	Z-RFC-P22	Z-RFC-P23	Z-RFC-P30	Z-RFC-P31	Z-RFC-P43

Lateral Magnet Offset



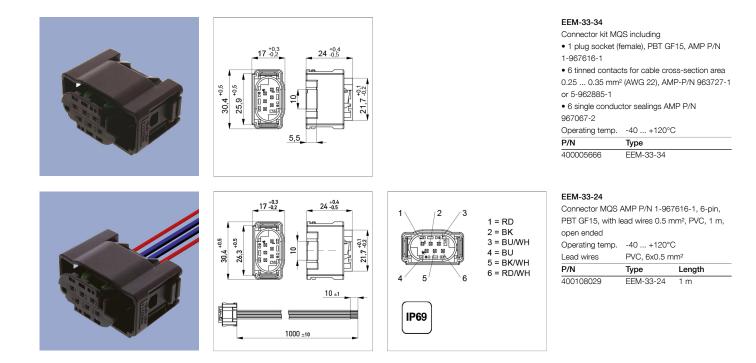
Lateral magnet offset will cause additional linearity error. The angle error, which is caused by radial displacement of sensor and position marker depends on the used position marker or magnet.

## Additional Linearity Error at Radial Displacement - One-channel Versions

Z-RFC-P02 / P04 / P08	Z-RFC-P41 / P43 / P47	Z-RFC-P03 / P30	Z-RFC-P18 / P28	Z-RFC-P19	Z-RFC-P22
Z-RFC-P20 / P23 / P31					
0.5 mm: ±0.4°	0.5 mm: ±0.4°	0.5 mm: ±1.4°	0.5 mm: ±0.7°	0.5 mm: ±1.3°	1.0 mm: ±0.8°
1.0 mm: ±1.1°	1.0 mm: ±1.1°	1.0 mm: ±3.7°	1.0 mm: ±1.3°	1.0 mm: ±2.6°	2.0 mm: ±1.8°
2.0 mm: ±3.5°	2.0 mm: ±3.5°	2.0 mm: -	2.0 mm: ±3.3°	2.0 mm: -	4.0 mm: ±5.4°
Z-RFC-P02 / P04 / P08	Z-RFC-P41 / P43 / P47	Z-RFC-P03 / P30	Z-RFC-P18 / P28	Z-RFC-P19	Z-RFC-P22
Z-RFC-P02 / P04 / P08 Z-RFC-P20 / P23 / P31	Z-RFC-P41 / P43 / P4/	Z-RFC-P03 / P30	Z-RFC-P18 / P28	Z-RFC-P19	Z-RFC-P22
0.5 mm: +0.7°	0.5 mm: +0.7°	0.5 mm; +2.5°	0.5 mm: +1.1°	0.5 mm; +2.3°	1.0 mm: +1.1°
0.5 mm. ±0.7	0.5 mm. ±0.7	0.5 mm. ±2.5	0.5 mm. ±1.1	0.5 mm. ±2.5	1.0 mm. ±1.1
1.0 mm: ±1.8°	1.0 mm: ±1.8°	1.0 mm: ±6.4°	1.0 mm: ±2°	1.0 mm: ±4.5°	2.0 mm: ±2.4°
2.0 mm: ±5,2°	2.0 mm: ±5.2°	2.0 mm: -	2.0 mm: ±4.6°	2.0 mm: -	4.0 mm: ±6.7°



# Connector System MQS





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